Dynamics of Continuous, Discrete and Impulsive Systems Series A: Mathematical Analysis **31 (2024)** 279-286 Copyright ©2024 Watam Press

http://www.watam.org

## PERIODIC ORBITS OF CONTINUOUS-DISCONTINUOUS PIECEWISE DIFFERENTIAL SYSTEMS WITH FOUR PIECES SEPARATED BY THE CURVE XY = 0 AND FORMED BY LINEAR HAMILTONIAN SYSTEMS

Jaume Llibre<sup>1</sup> and Tayeb Salhi<sup>2</sup>

 $^{1}$ Departament de Matemàtiques, Universitat Autònoma de Barcelona, 08193 Bellaterra, Barcelona, Catalonia, Spain

<sup>2</sup>Department of Mathematics University Mohamed El Bachir El Ibrahimi, Bordj Bou Arreridj 34265, El-anasser, Algeria

**Abstract.** In recent years there has been a significant interest in studying the piecewise differential systems, mainly due to their wide range of applications in modeling natural phenomena. Understanding the dynamics of such systems in the plane is a significant challenge, particularly when we want to study their periodic orbits and, more specifically, their limit cycles. Consequently, numerous studies have been dedicated to investigating periodic orbits' existence or non-existence within continuous and discontinuous piecewise differential systems. However, to the best of our knowledge, this paper is one of the pioneering works analyzing the periodic orbits within a specific class of piecewise differential systems, the ones exhibiting continuity in one part of the separation line while being discontinuous in the other part.

Our study analyzes the periodic orbits of the piecewise differential systems formed by four pieces, having the curve xy = 0 as the separation line. In each piece, there is an arbitrary linear Hamiltonian system. Moreover, we assume that these piecewise differential systems exhibit continuity along the x-axis while discontinuous along the y-axis

**Keywords.** Linear focus, linear center, quadratic weak focus, quadratic center, limit cycle, discontinuous piecewise differential system.

AMS (MOS) subject classification: Primary 34C05, 34A34.

## 1 Introduction

A dynamical system is any system that changes over time, and ODEs provide a concise and elegant way to capture this behavior. A dynamical system can be defined as a function that describes the time evolution of a point in an ambient space, such as a parametric curve. Examples of dynamical systems that can be modeled with ODEs include the oscillation of a clock pendulum, the flow of water through a pipe, the motion of particles in the air, and