

## INFINITE-DIMENSIONAL LYAPUNOV VECTOR FUNCTION AND STABILITY OF FIXED POINTS OF DISCRETE DYNAMICAL SYSTEMS IN SPACE $\text{conv } \mathbb{R}^n$

I.V. Atamas<sup>1</sup> and V.I. Slyn'ko<sup>2</sup>

<sup>1</sup> Department of Algebra and Mathematical Analysis  
Bohdan Khmelnytsky National University of Cherkasy, Cherkasy, Ukraine

<sup>2</sup> Department of Processes Stability  
S.P. Timoshenko Institute of Mechanics of NAS of Ukraine, Kiev, Ukraine

**Abstract.** The stability of fixed points of the discrete dynamical systems in space  $\text{conv } \mathbb{R}^n$  is investigated. A construction of the Lyapunov vector function with a countable number of components is proposed. Using the theorems on the embedding the space  $\text{conv } \mathbb{R}^n$  into the Banach space  $C(S^{n-1})$  and some results of the geometry of convex bodies, established in the papers of A.D. Aleksandrov, a difference equation in variations in the space  $C(S^{n-1})$  is constructed. An example of the stability study of a discrete dynamical system in the space  $\text{conv } \mathbb{R}^n$  is given.

**Keywords.** Lyapunov vector function, fixed point, discrete dynamical system, stability, mixed volume.

**AMS (MOS) subject classification:** 93D30; 52A39.

## 1 Introduction

Method of Lyapunov vector functions [5, 7] is one of the most effective method for studying the stability of motion of complex dynamical systems. The set-valued dynamical systems, in particular, the differential equation with Hukuhara derivative (set differential equations) have been investigated in many papers, among which we note the monograph [6]. This monograph presents the results of the general theory of set differential equations (SDEs) and theorems of the direct Lyapunov method and comparison method. In monograph [13], relationship of solutions of SDEs with the solution of differential inclusions has been shown. We also note the role of dynamical systems in space  $\text{conv } \mathbb{R}^n$  for the theory of controlled systems, since the evolution of attainability sets of linear controlled systems (integral funnels) is described by this class of dynamical systems (see [3]).

The aim of this work is to develop a method of Lyapunov vector functions with regard to the stability problem of fixed points of discrete dynamical