

## AN ITERATIVE ALGORITHM FOR FINDING A COMMON SOLUTION OF FIXED POINT PROBLEM AND SYSTEM OF EQUILIBRIUM PROBLEMS

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**Abstract.** Our aim in this paper is to prove strong convergence theorem for approximation of fixed point of a  $\lambda$ -strictly pseudo-contractive mapping which is also a common solution to a finite system of equilibrium problems in a real Hilbert space by modifying the iterative scheme of Li and Yao [M. Li, Y. Yao; Strong convergence of an iterative algorithm for  $\lambda$ -strictly pseudo-contractive mappings in Hilbert spaces, An. St. Univ. Ovidius Constanta 18 (1)(2010), 219-228]. Our result complements the result of Li and Yao in a real Hilbert space.

**Keywords.** Equilibrium problems;  $\lambda$ -strictly pseudocontractive mapping; strong convergence; Hilbert spaces, fixed point.

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### 1 Introduction

Let  $H$  be a real Hilbert space and  $K$  a nonempty, closed and convex subset of  $H$ . A mapping  $T : K \rightarrow K$  is said to be *nonexpansive* if

$$\|Tx - Ty\| \leq \|x - y\|, \quad \forall x, y \in K, \quad (1)$$

and  $T : K \rightarrow K$  is said to be  *$\lambda$ -strictly pseudocontractive* if for  $0 \leq \lambda < 1$ ,

$$\|Tx - Ty\|^2 \leq \|x - y\|^2 + \lambda \|(I - T)x - (I - T)y\|^2, \quad \forall x, y \in K. \quad (2)$$

In a Hilbert space  $H$ , we can show that (2) is equivalent to

$$\langle Tx - Ty, x - y \rangle \leq \|x - y\|^2 - \frac{1 - \lambda}{2} \|(I - T)x - (I - T)y\|^2. \quad (3)$$

A point  $x \in K$  is called a *fixed point* of  $T$  if  $Tx = x$ . The set of fixed points of  $T$  is denoted by  $F(T)$ .