

SYNTHESIS OF OPTIMAL CONTROLLED TRAJECTORIES WITH CHATTERING ARCS

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Abstract. A field theoretic approach that is based on the method of characteristics is outlined to prove the optimality of a synthesis of controlled trajectories that contains chattering arcs. Since the corresponding controls are not piecewise continuous - they switch infinitely many times on finite intervals - the classical argument by Boltyansky to prove differentiability of the associated value function is no longer applicable. This difficulty is overcome by matching the *two* parameterized families of extremal controlled trajectories that correspond to the constant controls $u = \pm 1$ at the switching surfaces in a continuously differentiable way.

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