

## Erratum to “Non-Fragile Controllers of Peak Gain Minimization For Uncertain Systems Via LMI Approach”

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In paper [1], an important condition of the main Lemma (Lemma 2.2) was missed. The corrected Lemma should be as follows.

**Lemma 2.2.** Given a symmetric matrix  $G$ , and nonzero matrices  $M$ ,  $N$ . Then

$$G + M\Delta N + N^T \Delta^T M^T \leq 0$$

for all  $\Delta$  satisfying  $\Delta^T \Delta \leq I$  if and only if there exists a constant  $\epsilon > 0$  such that

$$G + \epsilon MM^T + \frac{1}{\epsilon} N^T N \leq 0.$$

The condition that  $M$  and  $N$  are nonzero matrices is necessary. When  $G = 0$ ,  $N = 0$  and  $M = I$ , the result does not hold. In fact, the condition was used in the original proof in [1]. However, the corresponding results in paper [1] are not affected by the above correction. For example,  $E, H_A$  in Theorem 3.1 are not zero matrices. If this is not the case, then the uncertain system is a trivial one. Thus,  $E, PH_A$  are nonzero because of the nonsingularity of  $P$ . So, Theorem 3.1 satisfies the condition of the corrected Lemma. Other results related to uncertainties also hold under the corrected Lemma.

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## References

- [1] F. Hao, T. Chu, L. Huang, and L. Wang, “Non-fragile controllers of peak gain minimization for uncertain systems via LMI approach”, *Dynamics of Continuous, Discrete and Impulsive Systems, Series B: Applications & Algorithms* 10 (2003) 681-693.