

## DECENTRALIZED SUPERVISORY CONTROLLER DESIGN FOR DISCRETE-EVENT SYSTEMS USING OVERLAPPING DECOMPOSITIONS AND EXPANSIONS

Aydın Aybar and Altuğ İftar

aaybar@anadolu.edu.tr    aiftar@anadolu.edu.tr  
Department of Electrical and Electronics Engineering  
Anadolu University  
26470 Eskişehir, Turkey

**Abstract.** A decentralized supervisory controller design approach for discrete-event systems (DESS) modeled by automata or formal languages is presented. The controller is designed in order to lead the DES to certain desired marked states, in the sense that, from any state, which is reachable from the initial state, there exists a finite string of events which leads to one of the marked states. The controller design approach is based on overlapping decompositions and expansions. To apply the proposed approach, the automaton of the given DES is first decomposed overlappingly and expanded to obtain disjoint subautomata. Next, a controller is designed for each disjoint subautomaton. These controllers are then combined to obtain a controller for the expanded DES. In the final phase, a controller for the original DES is obtained from the controller determined for the expanded DES. It is proved that this final controller leads the original DES to the desired marked states. The computational complexity of the proposed design approach, relative to the computational complexity of a centralized approach is also discussed.

**Keywords.** Decentralized control, overlapping decompositions, discrete-event systems, supervisory control, automata, formal languages.

## 1 Introduction

Today, many systems, especially man-made systems such as manufacturing systems, communication systems, and transportation systems, are described by occurrence of certain events. Such systems are commonly named as discrete-event systems (DESS). *Automata* and *formal languages* [11, 9] are the two most common modeling approaches for these systems. Supervisory control [27] is commonly used to control such systems. Decentralized supervisory control has also been investigated in many works (e.g., [27, 25, 28, 10]).

In this work, we consider the problem of designing a decentralized supervisory controller for a DES, modeled by an automaton or equivalently by a